

Vector Analysis

Vector Fields

Suppose a region in the plane or space is occupied by a moving “fluid” such as air or water. Imagine this “fluid” is made up of a very large number of particles that at any instant of time a given particle has velocity vector \mathbf{v} . The set of these velocity vectors is what we call a **vector field**. If we examine these velocities we understand that they will vary from position to position.

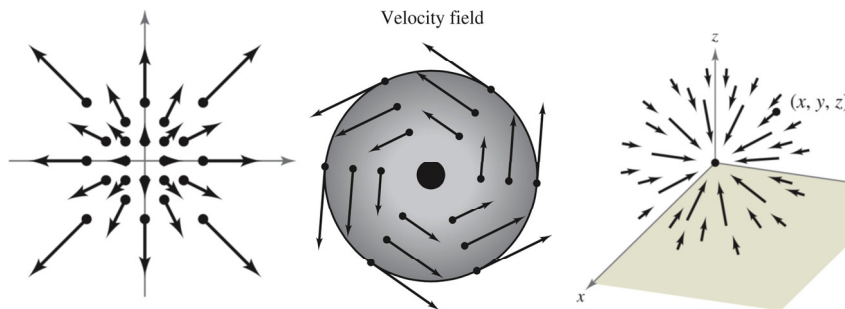
Some common examples of vector fields: wind shear off an object, gravitational fields, electric and magnetic fields, etc...

Vector Field:

A **vector field** in \mathbb{R}^2 or \mathbb{R}^3 respectively is a function \mathbf{F} that assigns to each point (x,y) or (x,y,z) respectively a 2-dimensional or 3-dimensional vector $\mathbf{F}(x,y)$ or $\mathbf{F}(x,y,z)$ where

$$\mathbf{F}(x,y) = \langle F_1(x,y), F_2(x,y) \rangle \text{ or } \mathbf{F}(x,y,z) = \langle F_1(x,y,z), F_2(x,y,z), F_3(x,y,z) \rangle$$

In general, a vector field is a function whose domain is the set of points in \mathbb{R}^2 or in \mathbb{R}^3 and whose range is a set of vectors in V^2 or V^3 .



A **unit vector field** is a vector field \mathbf{F} such that $\|\mathbf{F}(P)\| = 1$ for all points P in the domain. A vector field \mathbf{F} is called a **radial vector field** if $\mathbf{F}(P)$ depends only on a distance r from point P to the origin.

An important example of a unit radial vector field is:

$$\mathbf{e}_r = \left\langle \frac{x}{r}, \frac{y}{r}, \frac{z}{r} \right\rangle \text{ where } r = \sqrt{x^2 + y^2 + z^2}$$

We have already worked with one type of vector field in the gradient. The **gradient vector field** of a differentiable function $f(x,y,z)$ is the field of gradient vectors given by:

$$\nabla f = \mathbf{F}(x,y,z) = \langle f_x, f_y, f_z \rangle$$

This type of vector field is also known as a **conservative vector field**, and f is called a **potential function** for ∇f .

Ex: Find the gradient vector field for the potential function

$$f(x, y, z) = xy + yz^2$$

How would we know a vector field is conservative, that is it came from the partial derivatives of a potential function?

Cross-Partial Property of Conservative Vector Fields:

If a vector field $\mathbf{F}(x, y, z) = \langle F_1, F_2, F_3 \rangle$ is conservative, then

$$\frac{\partial F_1}{\partial y} = \frac{\partial F_2}{\partial x}, \frac{\partial F_2}{\partial z} = \frac{\partial F_3}{\partial y}, \frac{\partial F_3}{\partial x} = \frac{\partial F_1}{\partial z}$$

If $\mathbf{F}(x, y) = \langle F_1, F_2 \rangle$ then only the first equality has to hold

Ex: Show that $\mathbf{F}(x, y, z) = \langle 3, 1, 2 \rangle$ is conservative. Would any constant vector field be conservative?

Ex: Is $\mathbf{F}(x, y) = \langle 5y^3, 15xy \rangle$ conservative?

Ex: Is $\mathbf{F}(x, y, z) = \langle e^x \cos y, -e^x \sin y, 2 \rangle$ conservative?

Let \mathbf{F} be a vector field on a simply connected domain D (domain has no “holes”). If \mathbf{F} satisfies the cross partials condition, then \mathbf{F} is conservative and therefore has a potential function.

If f is a potential function for \mathbf{F} that $\frac{\partial f}{\partial x} = F_1, \frac{\partial f}{\partial y} = F_2$, etc. or another way to look at it is $\int F_1 dx = \int F_2 dy = \dots = f(x, y, \dots)$

Ex: Determine if $\mathbf{F}(x, y) = \langle xy^2, x^2y \rangle$ is conservative, if so find its potential function.

Ex: Determine if $\mathbf{F}(x, y, z) = \langle yz, xy, xy + 2z \rangle$ is conservative, if so find its potential function.

Line Integrals

A **line integral** (curve integral) is similar to a single integral except instead of integrating over an interval we integrate over a curve. These integrals are used to solve problems like fluid flow, electricity, forces and magnetism.

Like all integrals this line integral is defined through a process of subdivisions, summations, and limits. We divide C into n consecutive arcs, choose a sample point P_i in each arc C_i and form a Riemann sum.



Partition of C into N small arcs

Choice of sample points P_i in each arc

FIGURE 1 The curve C is divided into N small arcs.

$$\sum_{i=1}^n f(P_i)(\text{length of } C_i) = \sum_{i=1}^n f(P_i)\Delta s_i$$

The line integral of f over C is

$$\int_C f(x, y, z) ds = \lim_{\Delta s_i \rightarrow 0} \sum_{i=1}^n f(P_i)\Delta s \text{ where } ds \text{ is the arc length differential}$$

Computing a Scalar Line Integral:

Let $\mathbf{r}(t)$ be a parameterization of a curve C for $a \leq t \leq b$. If $f(x, y, z)$ and $\mathbf{r}'(t)$ are continuous, then

$$\int_C f(x, y, z) ds = \int_a^b f(\mathbf{r}(t)) \|\mathbf{r}'(t)\| dt$$

Ex: Evaluate $\int_C \sqrt{x^2 + y^2} ds$ along the curve $\mathbf{r}(t) = \langle 4 \cos t, 4 \sin t, 3t \rangle$;
 $-2\pi \leq t \leq 2\pi$

Ex: Evaluate $\int_C (xy + y + z) ds$ along $\mathbf{r}(t) = \langle 2t, t, 2 - 2t \rangle$ on $0 \leq t \leq 1$

Vector Line Integrals

When you carry a backpack up a mountain you do work against the earth's gravitational field. The work or energy expended is an example of quantity represented by a vector line integral (work done by force).

Computing a Vector Line Integral (Work Done by Force over a Curve in Space):

Suppose $\mathbf{F}(x, y, z) = \langle F_1(x, y, z), F_2(x, y, z), F_3(x, y, z) \rangle$ represents a force throughout a region in space and suppose $\mathbf{r}(t) = \langle g(t), h(t), k(t) \rangle$, $a \leq t \leq b$ is a smooth curve C in the region. Then the work done by \mathbf{F} over C defined by $\mathbf{r}(t)$ from a to b is:

$$W = \int_C \mathbf{F} ds = \int_C \mathbf{F} \cdot \mathbf{T} ds = \int_a^b \mathbf{F}(\mathbf{r}(t)) \cdot \mathbf{r}'(t) dt$$

This integral is known as a vector line integral.

Another notation is $\int_C \mathbf{F} ds = \int_C F_1 dx + F_2 dy + F_3 dz$

Two big differences between vector line integrals and a line integrals (scalar line integrals) is scalar line integrals are integrating functions and vector line integrals are integrating vector fields over curves and, that a vector line integral depends on a direction along a curve.

Ex: Find the vector line integral for $\mathbf{F}(x, y, z) = \langle x, y, z \rangle$ along the path $\mathbf{r}(t) = \langle \cos t, \sin t, t \rangle$ for $0 \leq t \leq 3\pi$.

Ex: Find the work done by \mathbf{F} from $(0,0,0)$ to $(1,1,1)$ over the curve $\mathbf{r}(t) = \langle t, t^2, t^4 \rangle$ where $\mathbf{F} = \langle 3x^2 - 3x, 3z, 1 \rangle$.

Conservative Vector Fields

When a curve C is **closed**, has the same start and end point, then we say the line integral of \mathbf{F} is the **circulation** of \mathbf{F} around C .

Remember a conservative vector field \mathbf{F} possesses a function f such that $\mathbf{F} = \nabla f$

Fundamental Theorem of Conservative Vector Fields:

Assume the $\mathbf{F} = \nabla f$ on a domain D , so f is the potential function for \mathbf{F} .

1. If C is a path from point P to point Q in D then

$$\int_C \mathbf{F} ds = V(Q) - V(P)$$

\mathbf{F} is path-independent (all that matters is the start and end points)

2. The circulation around a closed path C ($P=Q$) is zero:

$$\oint_C \mathbf{F} ds = 0$$

Ex: Let $\mathbf{F}(x, y, z) = \langle 2xy + z, x^2, x \rangle$, evaluate $\int_C \mathbf{F} ds$ where C is a path from $P = (1, -1, 2)$ to $Q = (2, 2, 3)$.

Ex: Determine if $\mathbf{F}(x, y, z) = \langle 2xy - z, x^2 + 2y, 1 - x \rangle$ is conservative, if so find its potential function and evaluate its vector line integral where C is a curve from $(1, 0, 2)$ to $(2, 1, 3)$.

Green's Theorem

Remember that for a conservative vector field the circulation around a closed path is zero. For vector fields in the plane, Green's Theorem tells us what happens when \mathbf{F} is not conservative.

A **simple closed curve** is a curve that does not intersect itself.

If a domain D has boundary C where C is a simple closed curve then we can denote C as ∂D . The counterclockwise orientation of D is called the **boundary orientation**.

Notation:

If $\mathbf{F}(x, y) = \langle F_1, F_2 \rangle$ then

$$\int_C \mathbf{F} ds = \int_C F_1 dx + F_2 dy$$

Green's Theorem:

Let D be a domain whose boundary ∂D is a simple closed curve, oriented counterclockwise. Then

$$\oint_{\partial D} \mathbf{F} ds = \oint_{\partial D} F_1 dx + F_2 dy = \iint_D \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) dA$$

Ex: Compute the circulation of $\mathbf{F}(x, y) = \langle \sin x, x^2 y^3 \rangle$ around the triangular path C , where C goes from point $(0, 0)$ to $(2, 0)$ to $(2, 2)$ to $(0, 0)$.

Ex: Use Green's Theorem to evaluate

$$\int_C (\arctan(x^2) - y^2)dx + (x^2y - \log(y^2 + 1))dy$$

where C is the semicircle $y = \sqrt{4 - x^2}$ together with the line segment from $(-2, 0)$ to $(2, 0)$.

Stokes' Theorem

Stokes' Theorem can be regarded as a higher dimensional version of Green's Theorem. Whereas Green's Theorem relates to double integrals over a plane region D to a line integral around its plane boundary curve, Stokes' Theorem relates to a surface integral over a surface S to a line integral around the boundary curve of S (which is a space curve).

Surface Integrals

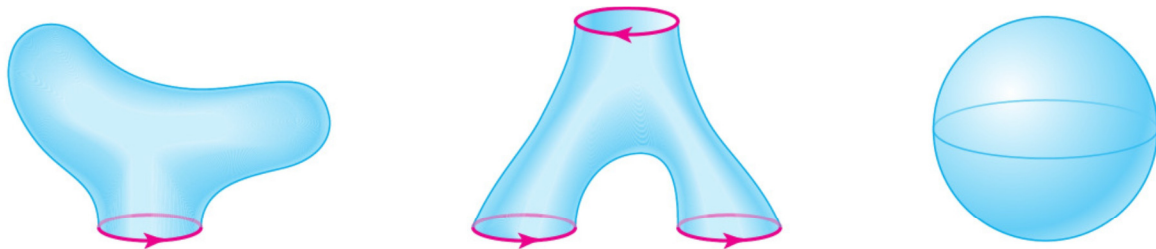
Rather than integrating a function or vector field over a curve we can integrate them over a surface. Surface integrals of vector fields represent **flux** or rates of flow through the surface, such as molecules across a cell membrane.

Because flux goes through a surface from one side to another we need to specify orientation of flow in the positive direction. The normal vector \mathbf{e}_n at a point on the surface points in the direction of orientation.

A vector surface integral is defined as $\iint_S \mathbf{F} \cdot d\mathbf{S} = \iint_S (\mathbf{F} \cdot \mathbf{e}_n)dS$

To compute this integral you would have to parameterize the surface S.

Stokes' theorem is an extension of Green's theorem to three dimensions in which circulation is related to a surface integrals. The following depicts three surfaces with different boundaries.



(A) Boundary consists of a single closed curve

(B) Boundary consists of three closed curves

(C) Closed surface (the boundary is empty)

FIGURE 1 Surfaces and their boundaries.

When S is oriented, we can specify an orientation of ∂S called the boundary orientation. Imagine that you are a unit normal vector walking along a boundary curve. The boundary orientation is the direction for which the surface is on your left as you walk.

The last thing we need to define is the curl. The **curl** of a vector field $\mathbf{F}(x, y, z) = \langle F_1, F_2, F_3 \rangle$ is the vector field defined by the symbolic determinant

$$\text{curl}(\mathbf{F}) = \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_1 & F_2 & F_3 \end{vmatrix} \text{ or } \text{curl}(\mathbf{F}) = \nabla \times \mathbf{F} \text{ where } \nabla = \left\langle \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right\rangle$$

Ex: Calculate the curl of $\mathbf{F} = \langle xy, e^x, y + z \rangle$

If \mathbf{F} is conservative then $\text{curl}(\mathbf{F}) = 0$

Stokes' Theorem:

Let S be oriented piecewise-smooth surface that is bounded by a simple, closed, piecewise-smooth boundary curve C with positive orientation. Let \mathbf{F} be a vector field whose components have continuous partial derivatives on an open region in \mathbb{R}^3 that contains S . Then

$$\oint_{\partial S} \mathbf{F} \cdot d\mathbf{s} = \iint_S \text{curl}(\mathbf{F}) \cdot d\mathbf{S}$$

The Divergence Theorem

The divergence theorem is an extension of Stokes' theorem for closed surfaces and triple integrals.

One term we need to define is the divergence of a vector field $\mathbf{F}(x, y, z) = \langle F_1, F_2, F_3 \rangle$ denoted $\text{div}(\mathbf{F})$.

$$\text{div}(\mathbf{F}) = \frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z} = \nabla \cdot \mathbf{F}$$

Ex: Evaluate the divergence of $\mathbf{F} = \langle e^{xy}, xy, z^4 \rangle$

The Divergence Theorem

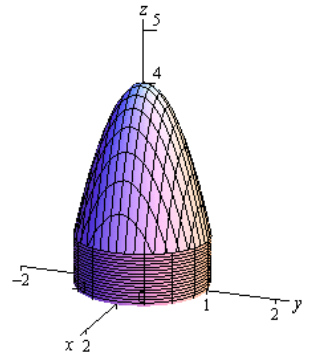
Let S be a closed surface that encloses a region W in \mathbb{R}^3 . Assume S is piecewise smooth and is oriented by normal vectors pointing to the outside of W . Let \mathbf{F} be a vector field whose domain contains W . Then

$$\iint_S \mathbf{F} \cdot d\mathbf{S} = \iiint_W \text{div}(\mathbf{F}) dV$$

Ex: Find the flux of a vector field $\mathbf{F}(x, y, z) = z\mathbf{i} + y\mathbf{j} + x\mathbf{k}$ over the unit sphere $x^2 + y^2 + z^2 = 1$.

Ex: Use the divergence to evaluate $\iint_S \mathbf{F} dS$ where

$\mathbf{F}(x, y, z) = \langle xy, -\frac{1}{2}y^2, z \rangle$ and the surface consists of the three surfaces, $z = 4 - 3x^2 - 3y^2$, $1 \leq z \leq 4$ on the top, $x^2 + y^2 = 1$, $0 \leq z \leq 1$ on the sides, and $z = 0$ on the bottom.



Summary of the “Fundamental Theorems”

The Fundamental Theorem of Calculus:

$$\int_a^b F'(x) dx = F(b) - F(a) \text{ where } [a, b] \text{ is an interval over the x axis}$$

The Fundamental Theorem of Line Integrals:

$$\int_C \nabla f ds = f(Q) - f(P) \text{ where P and Q are end points over a smooth curve}$$

Green’s Theorem:

$$\oint_{\partial D} \iint_D \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) dA \text{ where D is the region bounded by a simple closed curve}$$

Stokes’ Theorem:

$$\oint_{\partial S} \mathbf{F} ds = \iint_S \text{curl}(\mathbf{F}) d\mathbf{S} \text{ where S is the surface with the boundary curve C}$$

Divergence Theorem:

$$\iint_S \mathbf{F} \cdot d\mathbf{S} = \iiint_W \text{div}(\mathbf{F}) dV \text{ where S is the boundary surface of the 3-D region W}$$